## A Note on an Iterative Method for Generalized Inversion of Matrices\*

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The iterative method of Schulz [4], [3] for matrix inversion was generalized in [1] as follows:

THEOREM 1. The sequence of matrices defined by

(1) 
$$X_{k+1} = X_k (2P_{R(A)} - AX_k) \qquad (k = 0, 1, \cdots)$$

where  $X_0$  is an  $n \times m$  complex matrix satisfying

(2) 
$$X_0 = A^* B_0$$
,  $B_0$  some nonsingular  $m \times m$  matrix,

(3) 
$$X_0 = C_0 A^*, \quad C_0 \text{ some nonsingular } n \times n \text{ matrix},$$

(4) 
$$||AX_0 - P_{R(A)}|| < 1$$
,  $(|| || any matrix norm [3])$ ,

(5) 
$$||X_0A - P_{R(A^*)}|| < 1,$$

converges to the generalized inverse  $A^+$  of A.

As pointed out in [1], the computational significance of the method (1) is limited by the need for knowledge of  $P_{R(A)}$  (and of  $P_{R(A^*)}$  if condition (5) is to be checked). This difficulty is evaded in the following theorem.

THEOREM 2. Let A be an arbitrary (nonzero) complex  $m \times n$  matrix of rank r and let

$$\lambda_1(AA^*) \geq \lambda_2(AA^*) \geq \cdots \geq \lambda_r(AA^*)$$

denote the nonzero eigenvalues of  $AA^*$ . If the real scalar  $\alpha$  satisfies

(6) 
$$0 < \alpha < \frac{2}{\lambda_1(AA^*)}$$

then the sequence defined by:

(7) 
$$X_0 = \alpha A^*$$

(8) 
$$X_{k+1} = X_k(2I - AX_k)$$
  $(k = 0, 1, \cdots).$ 

converges to  $A^+$  as  $k \to \infty$ .

*Proof.*  $X_0$  defined by (7), (6) satisfies (2), (3), (4) and (5). To prove that  $X_0$  of (7), (6) satisfies (4) we note that  $AA^+$  ( $=P_{R(A)}$ ) and  $AA^*$  are commuting Hermitian matrices with the same range space. The eigenvalues of the  $m \times m$  matrix:  $AX_0 - P_{R(A)} = \alpha AA^* - AA^+$  are therefore

(9) 
$$\begin{cases} \alpha \lambda_i (AA^*) - 1 & (i = 1, \cdots, r) \\ 0 & (i = r + 1, \cdots, m) \end{cases}$$

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and, by (6), are all: <1 in absolute value:

(10) 
$$|\lambda_i(\alpha AA^* - AA^+)| < 1 \qquad (i = 1, \cdots, m)$$

similarly

(11) 
$$|\lambda_i(\alpha A^*A - A^*A)| < 1 \qquad (i = 1, \cdots, n).$$

(Indeed the nonzero eigenvalues of  $(\alpha AA^* - AA^+)$ ,  $(\alpha A^*A - A^+A)$  are identical.) With the lub<sub>s</sub>-norm [3, p. 44] in (4) and (5), both hold because of (10) and (11). (Actually (10) and (11) suffice for the convergence of (8).)

Now the process (1) initiated with:  $X_0 = \alpha A^*$  retains the form [1, Eq. (12)]:

(12) 
$$X_k = C_k A^*$$
  $(k = 1, 2, \cdots)$ 

and since

$$A^*P_{\mathcal{R}(A)} = A^*$$

it follows that:

(14) 
$$X_k(2P_{R(A)} - AX_k) = X_k(2I - AX_k) \qquad (k = 0, 1, \cdots)$$

and the convergence of (8) follows from that of (1). Q.E.D.

Remarks.

a) Similarly, the sequence defined by

(15) 
$$X_{k+1} = (2I - X_k A) X_k \qquad (k = 0, 1, \cdots)$$

with  $X_0 = \alpha A^*$ , converges to  $A^+$ .

b) In using the method (8) it is not necessary to compute  $\lambda_1(AA^*)$ : Writing

$$AA^* = (b_{ij}) \qquad (i, j = 1, \dots, m)$$

we conclude from the Gershgorin theorem, [3] that:

$$\lambda_1(AA^*) \leq \max_{i=1,\cdots,m} \left\{ \sum_{j=1}^m |b_{ij}| \right\}.$$

Condition (6) can therefore be replaced, e.g. by

(16) 
$$0 < \alpha < \frac{2}{\max_{i=1,\cdots,m} \left\{ \sum_{j=1}^{m} |b_{ij}| \right\}}$$

c) Examples and applications will be given in [2].

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